

Overview

Lecture 1

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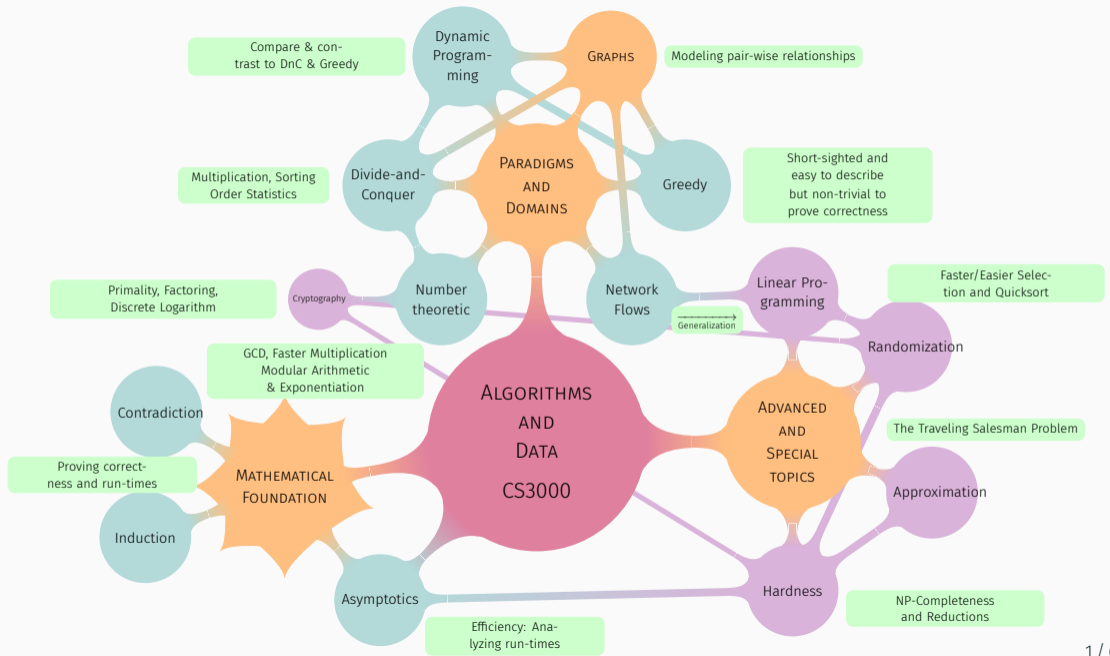
CS3000 Algorithms and Data

Map of CS3000 Algorithms Landscape

Goals and expected outcomes

1. Map of CS3000 Algorithms Landscape

“Algorithms are the computational content of proofs.” — Robert Harper, Benjamin C. Pierce et al.



2. Goals and expected outcomes

Algorithms:

- Well-specified procedure (recipe) for turning some *input* into some *output*.
- Efficiency in terms of resource constraints like time and space; parameterized by size of input (typically denoted using n).

This course will focus on

- various algorithm design strategies;
- proving correctness of algorithms;
- and analyzing efficiency (run-time) of algorithms.

Learning Outcomes

- **Create and Validate:** Efficient/performant algorithms for unseen but “everyday” problems.
- **Compare and Choose:** Among different algorithmic paradigms to choose most appropriate strategy.
- **Analyze and Evaluate:** Problem statements and constraints to determine their impact on algorithm design.
- **Modify and Employ:** Known algorithms and examples to new scenarios.
- **Research and Select:** Existing algorithms/implementations based on resource constraints.
- **Read, Examine, Recognize and Duplicate:** Algorithm descriptions given a reasonable amount of detail.

Drone Drop Durability

- *Question:* From what height can a drone fall without breaking apart?
- We want height $x \in \{1, 2, \dots, n\}$ such that drones break when falling from height $\geq x$. There is a known maximum height n after which the drone definitely breaks.
- *Test setup:* Try dropping a drone from height h , if it breaks, $x \leq h$ otherwise $x > h$.
- Assume that repeated dropping doesn't harm drone at all. No RSI (Repetitive Strain Injury).
- We'll look at what's minimum drops needed to find x when:
 1. No limit on number of drones. If one breaks, use next.
 2. There is only one test drone. If it breaks, you're done.
 3. There are two test drones. You have a *single* spare.

Drone Drop Durability – solutions (derived in-person)

1. No limit on number of drones. If one breaks, use next.

Binary search.

Need potentially $\log n$ drones, but drops also bounded by $\log n$.

2. There is only one test drone. If it breaks, you're done.

Cannot do better than testing heights one by one. Potentially need n drops.

3. There are two test drones. You have a single spare.

Use bracketing/binning. First drone tries at multiples of \sqrt{n} . Whenever it breaks, we have found a $(i \cdot \sqrt{n}, (i + 1) \cdot \sqrt{n}]$ bracket/bin in which to test spare drone.

